

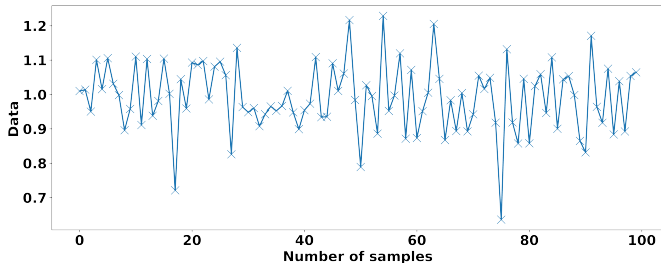
Cramér-Rao Lower Bound

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Overview

- 1 Recap
- 2 Score function and Regularity conditions
- 3 Fisher information
- 4 CRLB theorem
- 5 CRLB for the Gaussian models

Example



Consider a process e.g., a constant in noise

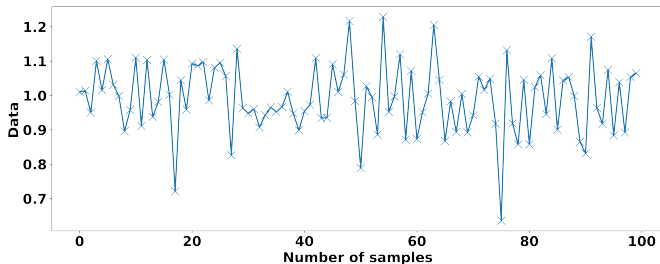
$$x[n] = A + w[n], \quad n = 0, \dots, N - 1,$$

where, we assume

- A is deterministic and *unknown*,
- $w[n]$ is a zero-mean random process with variance σ^2 ,
- $x[n]$ is the measured data.

How can we estimate A ?

Example



Potential estimators for A

- $\hat{A}_1 = x[0]$
- $\hat{A}_2 = \frac{1}{N} \sum_{n=0}^{N-1} x[n]$
- $\hat{A}_3 = \frac{a}{N} \sum_{n=0}^{N-1} x[n]$, for some constant a
- ...

Which estimator is *optimal* ? Estimator is also a random variable

Moments

Mean:

- $\mathbb{E}(\hat{A}_1) = \mathbb{E}(x[0]) = A$
- $\mathbb{E}(\hat{A}_2) = \mathbb{E}\left(\frac{1}{N} \sum_{n=0}^{N-1} x[n]\right) = \frac{1}{N} \sum_{n=0}^{N-1} \mathbb{E}(x[n]) = A$
- $\mathbb{E}(\hat{A}_3) = \mathbb{E}\left(\frac{a}{N} \sum_{n=0}^{N-1} x[n]\right) = \frac{a}{N} \sum_{n=0}^{N-1} \mathbb{E}(x[n]) = aA$

Variance:

- $\text{var}(\hat{A}_1) = \sigma^2$
- $\text{var}(\hat{A}_2) = \text{var}\left(\frac{1}{N} \sum_{n=0}^{N-1} x[n]\right) = \frac{1}{N} \sum_{n=0}^{N-1} \text{var}(x[n]) = \frac{\sigma^2}{N}$
- $\text{var}(\hat{A}_3) = \text{var}\left(\frac{a}{N} \sum_{n=0}^{N-1} x[n]\right) = \frac{a^2}{N} \sum_{n=0}^{N-1} \text{var}(x[n]) = \frac{a^2 \sigma^2}{N}$

Note:

- \hat{A}_1, \hat{A}_2 are *unbiased* estimators,
- \hat{A}_2 is *more efficient* than \hat{A}_1 .

Is there an *optimal* estimator ?

Optimality criterion

Let $\hat{\theta} = g(\mathbf{x}) = [x[0], x[1], x[N - 1]]$ be an estimator of θ , then

Mean square error (MSE):

$$\begin{aligned}mse(\hat{\theta}) &= \mathbb{E} \left[(\hat{\theta} - \theta)^2 \right] = \mathbb{E} \left\{ \left[(\hat{\theta} - \mathbb{E}(\hat{\theta})) + (\mathbb{E}(\hat{\theta}) - \theta) \right]^2 \right\} \\ &= \mathbb{E} \left[(\hat{\theta} - \mathbb{E}(\hat{\theta}))^2 \right] + (\mathbb{E}(\hat{\theta}) - \theta)^2 = \underbrace{\text{var}(\hat{\theta})}_{\text{variance}} + \underbrace{(\mathbb{E}(\hat{\theta}) - \theta)^2}_{\text{bias}},\end{aligned}$$

Unbiased estimators: If θ is an unbiased estimator, then

$$\mathbb{E}(\hat{\theta}) = \int g(\mathbf{x})p(\mathbf{x}; \theta)d\mathbf{x} = \theta \quad \text{for all } \theta,$$

where $p(\mathbf{x}; \theta)$ is the probability density function. In other words, for an unbiased estimator

$$\text{bias}(\theta) = \mathbb{E}(\hat{\theta}) - \theta = 0.$$

Minimum Variance Unbiased Estimator (MVU)

- Constrain the bias of the MSE to zero, i.e., $\mathbb{E}(\hat{\theta}) = \theta$, then

$$mse(\hat{\theta}) = \mathbb{E} \left[(\hat{\theta} - \mathbb{E}(\hat{\theta}))^2 \right] + (\mathbb{E}(\hat{\theta}) - \theta)^2 = \mathbb{E} \left[(\hat{\theta} - \mathbb{E}(\hat{\theta}))^2 \right]$$

where $\hat{\theta}$ is an unbiased estimator, and let

$$var(\hat{\theta}) \leq var(\tilde{\theta})$$

for any other unbiased estimator $\tilde{\theta}$, then $\hat{\theta}$ is the MVU for all θ .

- *Does a MVU exist i.e., an unbiased estimator with min. variance for all θ ?*

Example 1

Consider the measurement data $X = [X_0, X_2, \dots, X_{N-1}]$, where each sample is normally distributed as $\mathcal{U}[0, \theta]$, and the samples are IID i.e.,

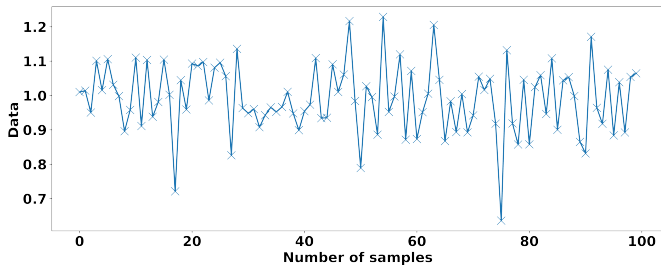
$$p(x_n; \theta) = \frac{1}{\theta} \text{ iff. } x_n \in [0, \theta] \text{ or } p(x_n; \theta) = 0$$

Which of the following are unbiased estimators ?

- A $\hat{\theta}_1 = 2 \sum_{n=0}^{N-1} x[n]$
- B $\hat{\theta}_2 = 2x[0]$
- C $\hat{\theta}_3 = 2N^{-1} \sum_{n=0}^{N-1} x[n]$
- D $\hat{\theta}_4 = \max(X)$

Do we have an MVU estimator ?

Example



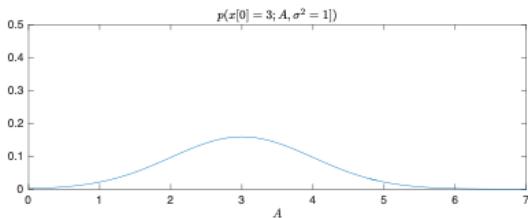
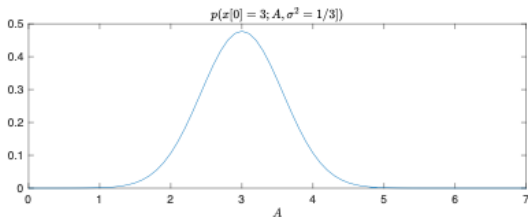
Consider the signal model

$$x[n] = A + w[n], \quad n = 0, \dots, N - 1,$$

where, we assume

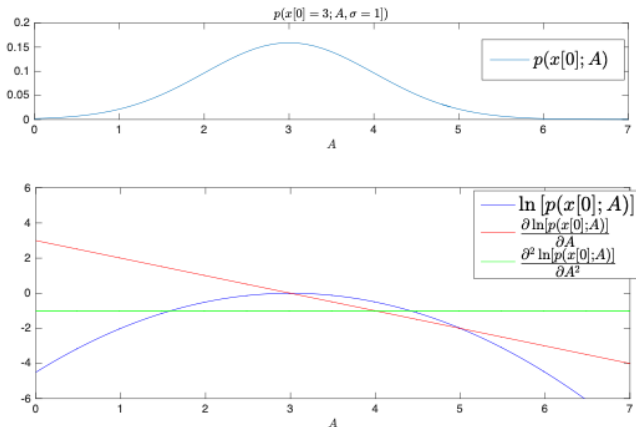
- A is deterministic and *unknown*,
- $w[n] \sim \mathcal{N}(0, \sigma^2)$,
- $x[n]$ is the measured data.

Observation (1)



- Consider a single realization: $x[0] = A + w[0]$ and the PDF $p(x[0]; A, \sigma^2)$
- Sharpness of the likelihood function determines the estimator accuracy

Observation (2)



- Measure the sharpness/curvature by $-\frac{\partial^2 \ln[p(x[0]; A)]}{\partial A^2} = 1$

Score function

- The *score* function is the gradient of the log-likelihood function

$$s(\mathbf{x}; \theta) = \frac{\partial \ln p(\mathbf{x}; \theta)}{\partial \theta},$$

which indicates the steepness of the log-likelihood function.

- Mean of the score function:

$$\mathbb{E} [s(\mathbf{x}; \theta)] = \mathbb{E} \left[\frac{\partial \ln p(\mathbf{x}; \theta)}{\partial \theta} \right]$$

Regularity conditions

- If $s(\mathbf{x}; \theta)$ exists and is finite, and

$$\int \frac{\partial p(\mathbf{x}; \theta)}{\partial \theta} d\mathbf{x} = \frac{\partial}{\partial \theta} \int p(\mathbf{x}; \theta) d\mathbf{x},$$

and the pdf $p(\mathbf{x}; \theta)$ satisfies the following *regularity condition*

$$\mathbb{E} [s(\mathbf{x}; \theta)] = \mathbb{E} \left[\frac{\partial \ln p(\mathbf{x}; \theta)}{\partial \theta} \right] = 0, \quad \text{for all } \theta,$$

unless the domain of the PDF for which it is nonzero depends on θ .

- If these *regularity conditions* are met, then we can estimate lower bounds on the variance of the estimator, and hopefully an MVU.

Example 2

Let $\{X_0, X_2, \dots, X_{N-1}\} \stackrel{i.i.d.}{\sim}$ Bernoulli (θ) distributed with

$$p(x_n; \theta) = \theta^{x_n} (1 - \theta)^{(1-x_n)} \quad n = 0, 1, \dots, N - 1$$

with an expected value $\mathbb{E}[x_n] = \theta$, and θ is the unknown parameter. Are the regularity conditions met ?

- A Yes, the regularity conditions are met
- B No, the regularity conditions are not met

Fisher information (1)

- The variance of the score function is the *Fisher information*

$$I(\theta) = -\mathbb{E} \left[\frac{\partial^2 \ln p(\mathbf{x}; \theta)}{\partial \theta^2} \right] = \mathbb{E} \left[\left(\frac{\partial \ln p(\mathbf{x}; \theta)}{\partial \theta} \right)^2 \right]$$

- Proof:* From the regularity conditions, we obtain

$$\frac{\partial}{\partial \theta} \mathbb{E} \left[\frac{\partial \ln p(\mathbf{x}; \theta)}{\partial \theta} \right] = 0 \Rightarrow \frac{\partial}{\partial \theta} \int \frac{\partial \ln p(\mathbf{x}; \theta)}{\partial \theta} p(\mathbf{x}; \theta) d\mathbf{x} = 0$$

or,

$$\int \left[\frac{\partial^2 \ln p(\mathbf{x}; \theta)}{\partial \theta^2} p(\mathbf{x}; \theta) + \frac{\partial \ln p(\mathbf{x}; \theta)}{\partial \theta} \frac{\partial p(\mathbf{x}; \theta)}{\partial \theta} \right] d\mathbf{x} = 0,$$

and rearranging the terms,

$$\begin{aligned} - \int \frac{\partial^2 \ln p(\mathbf{x}; \theta)}{\partial \theta^2} p(\mathbf{x}; \theta) d\mathbf{x} &= \int \left(\frac{\partial \ln p(\mathbf{x}; \theta)}{\partial \theta} \right)^2 p(\mathbf{x}; \theta) d\mathbf{x} \\ -\mathbb{E} \left[\frac{\partial^2 \ln p(\mathbf{x}; \theta)}{\partial \theta^2} \right] &= \mathbb{E} \left[\left(\frac{\partial \ln p(\mathbf{x}; \theta)}{\partial \theta} \right)^2 \right] \end{aligned}$$

Fisher information (2)

The Fisher information is

- Non-negative, and
- Additive for *independent* observations, i.e., when

$$\ln p(\mathbf{x}; \theta) = \sum_{n=0}^{N-1} \ln p(x[n]; \theta),$$

then

$$-\mathbb{E} \left[\frac{\partial^2 \ln p(\mathbf{x}; \theta)}{\partial \theta^2} \right] = \sum_{n=0}^{N-1} -\mathbb{E} \left[\frac{\partial^2 \ln p(x[n]; \theta)}{\partial \theta^2} \right]$$

and for *identically* distributed observations

$$I(\theta) = Ni(\theta), \quad \text{where} \quad i(\theta) = -\mathbb{E} \left[\frac{\partial^2 \ln p(x[n]; \theta)}{\partial \theta^2} \right]$$

Cramér-Rao Lower Bound theorem

- Assume the pdf $p(\mathbf{x}; \theta)$ satisfies the regularity condition:

$$\mathbb{E} \left[\frac{\partial \ln p(\mathbf{x}; \theta)}{\partial \theta} \right] = 0,$$

then the variance of any unbiased estimator $\hat{\theta}$ satisfies

$$\text{var}(\hat{\theta}) \geq \frac{1}{-\mathbb{E} \left[\frac{\partial^2 \ln p(\mathbf{x}; \theta)}{\partial \theta^2} \right]} = \frac{1}{\mathbb{E} \left[\left(\frac{\partial \ln p(\mathbf{x}; \theta)}{\partial \theta} \right)^2 \right]} = \frac{1}{I(\theta)}$$

- An estimator is *efficient* if it meets the CRLB with equality, in which case the estimator is the MVU.
- However, the converse is not necessarily true.

Example 3

Let $[X_0, X_2, \dots, X_{N-1}]$ be IID samples from a Bernoulli (θ) distribution with

$$p(x_n; \theta) = \theta^{x_n} (1 - \theta)^{(1-x_n)} \quad n = 0, 1, \dots, N - 1$$

with an expected value $\mathbb{E}[x_n] = \theta$, and θ is the unknown parameter. What is the CRB for the unknown θ ?

A $\text{var}(\hat{\theta}) \geq \frac{-\theta(1 + \theta)}{N}$

B $\text{var}(\hat{\theta}) \geq \frac{N}{\theta(1 - \theta)}$

C $\text{var}(\hat{\theta}) \geq \frac{\theta(1 - \theta)}{N}$

D $\text{var}(\hat{\theta}) \geq \frac{2\theta(1 - \theta)}{N}$

Finding the MVU estimator

- An unbiased estimator may be found that attains the bound for all θ iff

$$s(\mathbf{x}; \theta) = \frac{\partial \ln p(\mathbf{x}; \theta)}{\partial \theta} = I(\theta)(g(\mathbf{x}) - \theta),$$

for some function g and I , then $\hat{\theta} = g(\mathbf{x})$ is an estimator with

$$\text{Mean : } \mathbb{E}(\hat{\theta}) = \theta \quad \text{Variance : } \text{var}(\hat{\theta}) = \frac{1}{I(\theta)}.$$

Example 4(1)

$$x[n] = A + w[n] \quad n = 0, \dots, N - 1,$$

where $w[n] \sim \mathcal{N}(0, \sigma^2)$ is zero mean white Gaussian noise, i.e.,

$$\begin{aligned} p(\mathbf{x}; A) &= \prod_{n=0}^{N-1} \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left[-\frac{(x[n] - A)^2}{2\sigma^2}\right] \\ &= \frac{1}{(2\pi\sigma^2)^{N/2}} \exp\left[-\frac{\sum_{n=0}^{N-1} (x[n] - A)^2}{2\sigma^2}\right] \end{aligned}$$

Taking the log-likelihood, we have

$$\begin{aligned} s(\mathbf{x}; \mathbf{A}) &= \frac{\partial \ln \mathbf{p}(\mathbf{x}; \mathbf{A})}{\partial \mathbf{A}} = \frac{\partial}{\partial A} \left[-\frac{1}{2\sigma^2} \sum_{n=0}^{N-1} (x[n] - A)^2 \right] \\ &= \frac{1}{\sigma^2} \sum_{n=0}^{N-1} (x[n] - A) \end{aligned}$$

Example 4(2)

$$\begin{aligned}\frac{\partial \ln p(\mathbf{x}; A)}{\partial A} &= \frac{\partial}{\partial A} \left[-\frac{1}{2\sigma^2} \sum_{n=0}^{N-1} (x[n] - A)^2 \right] = \frac{1}{\sigma^2} \sum_{n=0}^{N-1} (x[n] - A) \\ &= \underbrace{\frac{N}{\sigma^2}}_{I(\theta)} \left(\underbrace{\frac{1}{N} \sum_{n=0}^{N-1} x[n]}_{g(\mathbf{x})} - \underbrace{A}_{\theta} \right)\end{aligned}$$

Recollect from the CRLB theorem

$$\text{var}(\hat{\theta}) \geq \frac{1}{-\mathbb{E} \left[\frac{\partial^2 \ln p(\mathbf{x}; \theta)}{\partial \theta^2} \right]} = \frac{1}{\mathbb{E} \left[\left(\frac{\partial \ln p(\mathbf{x}; \theta)}{\partial \theta} \right)^2 \right]}$$

and thus $\text{var}(\hat{A}) \geq \frac{\sigma^2}{N}$, where $\hat{A} = g(\mathbf{x})$.

CRLB for the general Gaussian model (1)

Let us assume a Gaussian distribution for the noise:

$$\mathbf{w} \sim \mathcal{N}(\mathbf{0}, \mathbf{C}_w) \Leftrightarrow p(\mathbf{w}) = \frac{1}{(2\pi)^{\frac{N}{2}} \det(\mathbf{C}_w)^{\frac{1}{2}}} \exp \left[-\frac{1}{2} \mathbf{w}^T \mathbf{C}_w^{-1} \mathbf{w} \right]$$

Then the *Gaussian model* is defined as

$$\mathbf{x} = \mathbf{h}(\theta) + \mathbf{w} \quad \mathbf{x} \sim \mathcal{N}(\mathbf{h}(\theta), \mathbf{C}_w)$$

or,

$$p(\mathbf{x}) = \frac{1}{(2\pi)^{\frac{N}{2}} \det(\mathbf{C}_w)^{\frac{1}{2}}} \exp \left[-\frac{1}{2} (\mathbf{x} - \mathbf{h}(\theta))^T \mathbf{C}_w^{-1} (\mathbf{x} - \mathbf{h}(\theta)) \right]$$

CRLB for the general Gaussian model (2)

Score:

$$\frac{\partial \ln p(\mathbf{x}; \theta)}{\partial \theta} = \frac{\partial \mathbf{h}^T(\theta)}{\partial \theta} \mathbf{C}_w^{-1} (\mathbf{x} - \mathbf{h}(\theta))$$

and

$$\frac{\partial^2 \ln p(\mathbf{x}; \theta)}{\partial \theta^2} = \frac{\partial^2 \mathbf{h}^T(\theta)}{\partial \theta^2} \mathbf{C}_w^{-1} (\mathbf{x} - \mathbf{h}(\theta)) - \frac{\partial \mathbf{h}^T(\theta)}{\partial \theta} \mathbf{C}_w^{-1} \frac{\partial \mathbf{h}(\theta)}{\partial \theta}.$$

Fisher information:

$$-\mathbb{E} \left[\frac{\partial^2 \ln p(\mathbf{x}; \theta)}{\partial \theta^2} \right] = \frac{\partial \mathbf{h}^T(\theta)}{\partial \theta} \mathbf{C}_w^{-1} \frac{\partial \mathbf{h}(\theta)}{\partial \theta}$$

CRLB:

$$\text{var}(\hat{\theta}) \geq \frac{1}{\frac{\partial \mathbf{h}^T(\theta)}{\partial \theta} \mathbf{C}_w^{-1} \frac{\partial \mathbf{h}(\theta)}{\partial \theta}}$$

CRLB for the linear Gaussian model

Consider the *linear Gaussian model*:

$$\mathbf{x} = \mathbf{h}\theta + \mathbf{w}, \quad \mathbf{w} \sim \mathcal{N}(\mathbf{0}, \mathbf{C}_w)$$

From CRLB for a General Gaussian model, we know

$$\frac{\partial \ln p(\mathbf{x}; \theta)}{\partial \theta} = \frac{\partial \mathbf{h}^T(\theta)}{\partial \theta} \mathbf{C}_w^{-1} (\mathbf{x} - \mathbf{h}(\theta)), \quad \text{var}(\hat{\theta}) \geq \frac{1}{\mathbf{h}^T \mathbf{C}_w^{-1} \mathbf{h}}$$

Furthermore,

$$\begin{aligned} \frac{\partial \ln p(\mathbf{x}; \theta)}{\partial \theta} &= \mathbf{h}^T \mathbf{C}_w^{-1} (\mathbf{x} - \mathbf{h}\theta) \\ &= \mathbf{h}^T \mathbf{C}_w^{-1} \mathbf{h} [(\mathbf{h}^T \mathbf{C}_w^{-1} \mathbf{h})^{-1} \mathbf{h}^T \mathbf{C}_w^{-1} \mathbf{x} - \theta] \end{aligned}$$

Thus, the MVU exists and its solution reaches the CRLB:

$$\hat{\theta} = (\mathbf{h}^T \mathbf{C}_w^{-1} \mathbf{h})^{-1} \mathbf{h}^T \mathbf{C}_w^{-1} \mathbf{x}$$

Summary

Key points:

- Score function is the first derivative of the log-likelihood function w.r.t. unknown parameter
- Regularity conditions are met, if the score exists, is finite and if the expectation of the score function equals zero.
- Fisher information is the covariance of the score function
- If the regularity conditions hold, then the CRLB is the inverse of the Fisher information, which gives the lowest achievable bound by an unbiased estimator.
- In certain cases, the MVU can be obtained from the score function, given the CRLB.

Next session:

- Practical estimators

Assignments

Solve:

- Kay-I, Problem 3.1: Show that the regularity condition does not hold for $x[n] \sim \mathcal{U}[0, \theta]$, which are IID.
- Kay-I, Problem 3.3: Consider the data $x[n] = Ar^n + w[n]$ for $n = 0, 1, \dots, N - 1$ where $w[n]$ is WGN with variance σ . Derive the CRLB for A , and show that an efficient estimator exists and find its variance.

Derivation:

- Kay-I, 3A: Derivation of scalar Parameter CRLB
- Kay-I, 3B: Derivation of vector Parameter CRLB
- Kay-I, 3C: Derivation of general Gaussian CRLB