

Signal Processing EE2S31

Digital Signal Processing Lecture 6: Quantization and round-off effects

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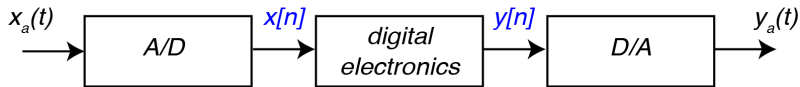
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Outline

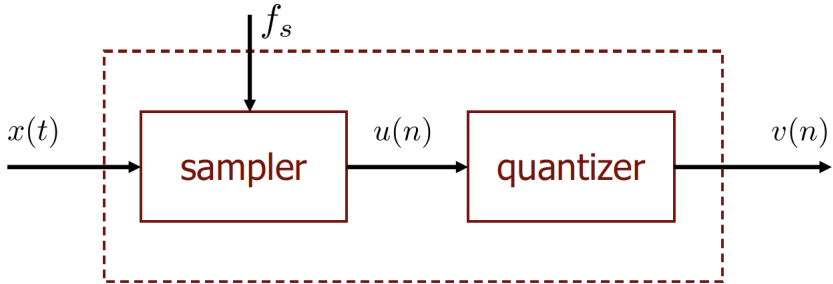
- Quantization
- Coding
- Its effect on digital filters

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A/D converter



Basic task: convert a continuous range of input amplitudes to a discrete set of digital code words.

A/D converters

- sampling
- quantization
- coding

A/D converters

- sampling → lecture 1, 2
- quantization
- coding

A/D converters

- sampling → lecture 1, 2
- quantization → a non-linear and non-invertible process that maps a given amplitude $x[n] = x_a(nT_s)$ at time $t = nT_s$ into an amplitude \hat{x}_k taken from a finite set of values (*quantization level* or *alphabet*)
- coding

A/D converters

- sampling → lecture 1, 2
- quantization → a non-linear and non-invertible process that maps a given amplitude $x[n] = x_a(nT_s)$ at time $t = nT_s$ into an amplitude \hat{x}_k taken from a finite set of values (*quantization level* or *alphabet*)
- coding → assigns a unique binary number (*code*) to each and every quantization level. This process is invertible (lossless).

Quantization

An L-level quantizer is characterized by

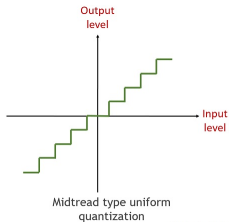
- a set of L+1 **decision thresholds** $x_1 < x_2 < \dots < x_{L+1}$ and
- a set $\hat{X} = \{\hat{x}_k, k = 1, \dots, L\}$ **reconstruction values** or **quantization levels**
- such that $\hat{x}[n] = \hat{x}_k$ if and only if $x_k \leq x[n] < x_{k+1}$, where $x_1 = -\infty$ and $x_{L+1} = \infty$
- where the intervals $I_k = [x_k, x_{k+1})$ are called **decision intervals** or **quantization cells**

The map $Q : X \rightarrow \hat{X}$, which is a staircase function by definition, is given by:

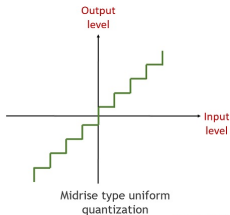
$$Q(x) = \hat{x}_k \text{ for } x \in I_k, k=1, \dots, L$$

Quantization

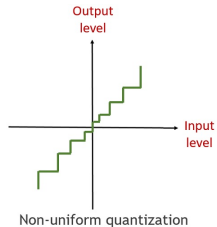
- uniform/non-uniform
- midtread/midrise



Electronics Desk



Electronics Desk



Electronics Desk

Quantization

The uniform (linear) quantizer:

- a $x_{k+1} - x_k = \Delta$
- a $\hat{x}_k = (x_{k+1} + x_k)/2 \Rightarrow \hat{x}_{k+1} - \hat{x}_k = \Delta$

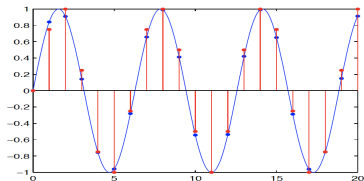
Δ is called the **step size** of the quantizer

The **quantization error** $z[n] = x[n] - \hat{x}[n]$ satisfies

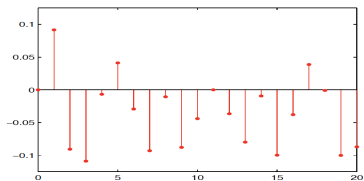
$$-\frac{\Delta}{2} \leq z[n] < \frac{\Delta}{2}$$

Example:

sampled signal (original (blue) and quantized (red))

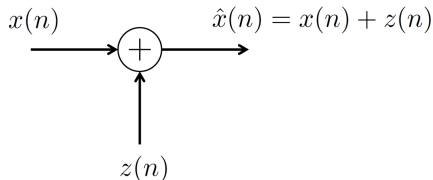
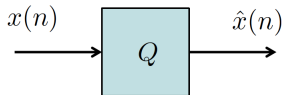


quantization error



Quantization error

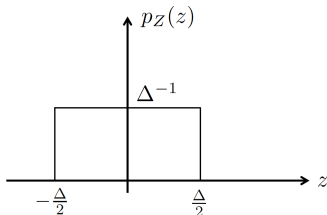
Mathematical model of quantization:



Assumptions:

- input signal $x[n]$ is the realization of a zero-mean WSS process
- quantization noise is white
- quantization noise is uncorrelated to the input

Quantization error



We further assume that the error $z[n]$ is uniformly distributed. Then, the quantization noise power (= variance) of a quantizer with resolution (= step size) Δ is

$$P_n = \sigma_e^2 = \frac{\Delta^2}{12}$$

- Proof? (Variance of a random variable with given PDF)
- Effective performance (hence effective accuracy) is below the theoretical value due to fabrication

Quantization noise

Signal-to-quantization noise ratio (SQNR):

- Let's denote the range of the quantizer with R
- Let's use $B + 1$ bits to represent the quantized values
- Then

$$\Delta = \frac{R}{2^{B+1}}$$

- Therefore, the SQNR is:

$$\begin{aligned} \text{SQNR} &= 10 \log_{10} \left(\frac{\sigma^2(x)}{\sigma^2(z)} \right) = 10 \log_{10} \frac{12\sigma^2(x)}{\Delta^2} = \\ &= 6,02B + 16,81 + 20 \log_{10} \left(\frac{\sigma(x)}{R} \right) \end{aligned}$$

Outline

- Quantization
- **Coding**
- Its effect on digital filters

Coding

The *coding* process assigns a unique binary number to each quantization level.

- Fixed point
 - Covers a fixed range of numbers
 - Fixed resolution
 - Dynamic range \uparrow
Resolution \downarrow
- Floating point
 - It can cover a much larger dynamic range
 - Varying resolution
 - consists of 2 parts:
mantissa and exponent

$$\Delta = \frac{R}{2^{B+1}} = \frac{x_{max} - x_{min}}{m - 1}, \text{ with } m = 2^b, b = B+1$$

$$X = M \cdot 2^E$$

Fixed-point representation

$$X = (b_{-A}, \dots, b_{-1}, b_0, b_1, \dots, b_B)_r = \sum_{i=-A}^B b_i r^{-i}$$

- r : radix or base; e.g. $r = 2$ for binary
- A : number of integer digits, B : number of fractional digits

Often used:

- $A = 0$ and $B = n - 1$
- This representation allows to represent quantized values between 0 to $1 - 2^{-B}$

Fixed-point signed binary format

There are various possible formats:

- signed-magnitude (SM)
- one's complement (1C)
- two's complement (2C)

Positive numbers are the same in all formats. Example:

- $X = (0.101)_2 = 2^{-1} + 2^{-3} = 1/2 + 1/8 = 5/8$

Negative numbers:

- $X_{SM} = (1.101)_2 = -(2^{-1} + 2^{-3}) = -(1/2 + 1/8) = -5/8$
- $X_{1C} = (1.010)_2 = -5/8$
- $X_{2C} = (1.011)_2 = -5/8$

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$$\downarrow \overline{b_i} = 1 - b_i$$

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- $X_{2C} = (1.011)_2 = -5/8$ ↓ $X_{2C} = X_{1C} + 00...01$

Fixed-point signed binary format

There are various possible formats:

- signed-magnitude (SM) **easy multiplication**
- one's complement (1C) **easy addition**
- two's complement (2C) **easy addition, larger range**

Positive numbers are the same in all formats. Example:

- $X = (0.101)_2 = 2^{-1} + 2^{-3} = 1/2 + 1/8 = 5/8$

Negative numbers:

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Quantization effects in digital filters

- Quantization of filter coefficients (9.5)
- Round-off effects in filter arithmetics (9.6.1)
- Statistical analysis of quantization effects (9.6.3)

Quantization effects in digital filters

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Quantization of filter coefficients

$$H(z) = \frac{B(z)}{A(z)} = \frac{\sum_{k=0}^M b_k z^{-k}}{1 - \sum_{k=0}^N a_k z^{-k}}$$

After quantization:

$$\hat{a}_k = a_k + \Delta a_k, \quad \hat{b}_k = b_k + \Delta b_k \quad (1)$$

As a result, the practically implemented transfer function changes as follows:

$$\hat{H}(z) = \frac{\hat{B}(z)}{\hat{A}(z)} = \frac{\sum_{k=0}^M \hat{b}_k z^{-k}}{1 - \sum_{k=0}^N \hat{a}_k z^{-k}} \quad (2)$$

Quantization of filter coefficients

As a consequence, the position of the poles and zeros change as well:

$$\hat{p}_k = p_k + \Delta p_k$$

$$\hat{z}_k = z_k + \Delta z_k$$

It can be shown that:

$$\Delta p_k = \sum_{l=1}^N \frac{p_k^{N-l}}{\prod_{k=1, m \neq k}^N (p_k - p_m)} \Delta a_l$$

Closely spaced poles give rise to large errors!

Quantization of filter coefficients

Strategies to minimize the error Δp_k , i.e. $|p_k - p_l|$:

- Realize higher order filters with one or two-pole filter sections
- note: one-pole filter sections require complex arithmetic
- solution: use second order sections with complex-conjugated poles
- complex-conjugated poles are sufficiently far, i.e. perturbation error will be under control

Quantization of filter coefficients

Even in two-pole filter sections, the structure used to implement the section plays an important role in the error caused by coefficient quantization.

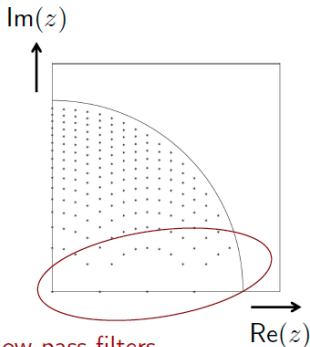
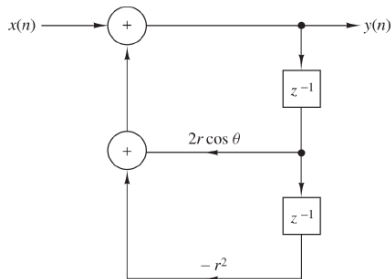
Consider the following filter, with poles at $z = re^{\pm j\theta}$

$$H(z) = \frac{1}{1 - 2r\cos\theta z^{-1} + r^2 z^{-2}}$$

Quantization of filter coefficients

Assuming 4-bit quantization:

- We need to quantize $2r \cos \theta$ and r^2
- What are the possible pole positions?
- Positions are non-uniformly distributed: poles lie on a circular arc with radius r , but we quantize r^2

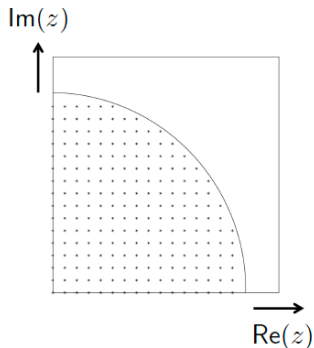
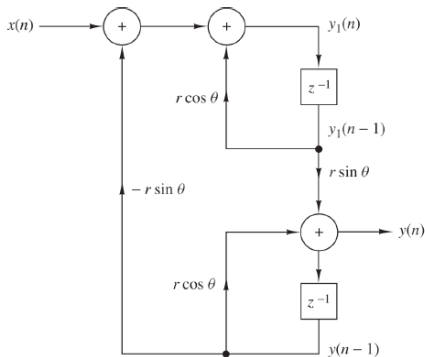


problems with low-pass filters

Quantization of filter coefficients

Alternative realization:

- We need to quantize $r \cos \theta$ and $r \sin \theta$.
- What are the possible pole positions?
- Both linear in r !



Quantization of filter coefficients

General strategy:

- choose a realization which yields uniform pole positions
- unfortunately there is no systematic design method
- for higher order structures, cascade is preferred over parallel form
- floating point arithmetic is preferred over fixed-point

Practice:

- Exercise 9.33

Quantization effects in digital filters

- Quantization of filter coefficients (9.5)
- **Round-off effects in filter arithmetics** (9.6.1)
- Statistical analysis of quantization effects (9.6.3)

Round-off effects in filters arithmetics

- In recursive systems, non-linearities due to finite-precision arithmetic operations cause periodic oscillations, called **limit cycles**.
- Let's consider the following single-pole system:

$$y(n) = ay(n-1) + x(n) \quad (3)$$

- The actual system, however, quantizes the result of the multiplication:

$$v(n) = Q[av(n-1)] + x(n) \quad (4)$$

Round-off effects in filters arithmetics

With $a < 1$ the ideal system (1) decays towards zero exponentially (i.e. $y(n) = a^n \rightarrow 0$ as $n \rightarrow \infty$). What about the actual system (2)?

- Let us assume 4-bit fixed-point arithmetic (plus sign bit)
- Let us also assume that the product is rounded upward
- Let us assume that $x(n) = \frac{15}{16}\delta(n)$

Round-off effects in filter arithmetics

The actual system's response $v(n)$ reaches a steady-state periodic output sequence, depending on the value a

TABLE 9.2 Limit Cycles for Lowpass Single-Pole Filter

n	$a = 0.1000 = \frac{1}{2}$	$a = 1.1000 = -\frac{1}{2}$	$a = 0.1100 = \frac{3}{4}$	$a = 1.1100 = -\frac{3}{4}$
0	0.1111 $(\frac{15}{16})$	0.1111 $(\frac{15}{16})$	0.1011 $(\frac{11}{16})$	0.1011 $(\frac{11}{16})$
1	0.1000 $(\frac{8}{16})$	1.1000 $(-\frac{8}{16})$	0.1000 $(\frac{8}{16})$	1.1000 $(-\frac{8}{16})$
2	0.0100 $(\frac{4}{16})$	0.0100 $(\frac{4}{16})$	0.0110 $(\frac{6}{16})$	0.0110 $(\frac{6}{16})$
3	0.0010 $(\frac{2}{16})$	1.0010 $(-\frac{2}{16})$	0.0101 $(\frac{5}{16})$	1.0101 $(-\frac{5}{16})$
4	0.0001 $(\frac{1}{16})$	0.0001 $(\frac{1}{16})$	0.0100 $(\frac{4}{16})$	0.0100 $(\frac{4}{16})$
5	0.0001 $(\frac{1}{16})$	1.0001 $(-\frac{1}{16})$	0.0011 $(\frac{3}{16})$	1.0011 $(-\frac{3}{16})$
6	0.0001 $(\frac{1}{16})$	0.0001 $(\frac{1}{16})$	0.0010 $(\frac{2}{16})$	0.0010 $(\frac{2}{16})$
7	0.0001 $(\frac{1}{16})$	1.0001 $(-\frac{1}{16})$	0.0010 $(\frac{2}{16})$	1.0010 $(-\frac{2}{16})$
8	0.0001 $(\frac{1}{16})$	0.0001 $(\frac{1}{16})$	0.0010 $(\frac{2}{16})$	0.0010 $(\frac{2}{16})$

Round-off effects in filter arithmetics

- The amplitude of the output during a limit cycle is confined to a certain range, called the *dead band* of the filter.
- For a single-pole filter the dead band is determined by:

$$|v_d(n)| \leq \frac{\frac{1}{2}2^{-b}}{1 - |a|}$$

Round-off effects in filter arithmetics

Practice

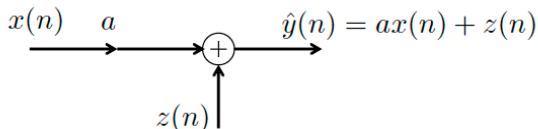
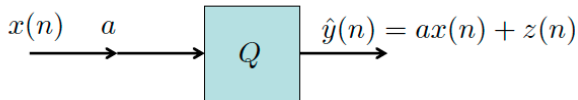
- Exercise 9.31
- Exercise 9.35

Outline

- Quantization of filter coefficients (9.5)
- Round-off effects in filter arithmetics (9.6.1)
- **Statistical analysis of quantization effects (9.6.3)**

Statistical analysis of quantization effects

The quantization error in multipliers can be modeled as additive, uniformly distributed white noise:



Superposition principle:

- The output of the system is equal to its response to the input plus its response to the quantization noise.
- In case of multiple noise sources, their effect is also additive.

Statistical analysis of quantization effects

The effect of the quantization noise depends on the transfer function of the noise source to the output of the filter.

Recap: filtering stochastic processes

Let g denote the impulse response of an LTI system. The response q of this LTI system to a white stochastic input z . Then,

$$\sigma_q^2 = \sigma_z^2 \sum_{n=-\infty}^{\infty} g(n)^2 = \frac{\sigma_z^2}{2\pi} \int_0^{2\pi} |G(e^{j\omega})|^2 d\omega$$

Statistical analysis of quantization effects

Let us consider a single-pole IIR filter:

$$h(n) = a^n u(n), \quad |a| < 1$$

Therefore

$$\sum_{n=-\infty}^{\infty} |h(n)|^2 = \sum_{n=-\infty}^{\infty} |a|^{2n} = \frac{1}{1 - |a|^2}$$

The noise power is enhanced relative to the input noise, depending on a .

Statistical analysis of quantization effects

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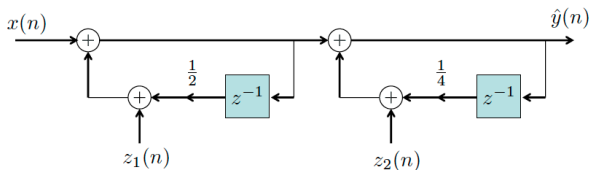
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Statistical analysis of quantization effects

Example:

$$H(z) = \frac{z^2}{(z - \frac{1}{2})(z - \frac{1}{4})} = \frac{z}{(z - \frac{1}{2})} \cdot \frac{z}{(z - \frac{1}{4})}$$



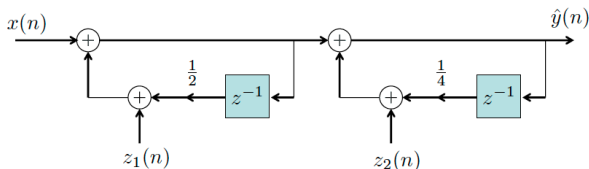
Let us consider a second-order filter $H(z)$, which is a cascade of two first-order filter sections $H_1(z)$ and $H_2(z)$.

- Due to superposition, the total noise power at the output is the sum of the output noise powers of $z_1(n]$ and $z_2(n]$.
- The transfer function of $z_1(n]$ to the output is $H(z)$, while the transfer function of $z_2(n]$ is $H_2(z)$.

Statistical analysis of quantization effects

Example:

$$H(z) = \frac{z^2}{(z - \frac{1}{2})(z - \frac{1}{4})} = \frac{z}{z - \frac{1}{2}} \cdot \frac{z}{z - \frac{1}{4}}$$



The impulse responses are as follows:

- $h_1(n) = (2(\frac{1}{2})^n - (\frac{1}{4})^n)u(n)$
- $h_2(n) = (\frac{1}{4})^n u(n)$

The output quantization noise power is:

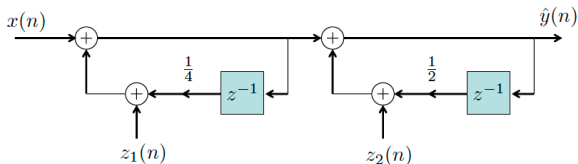
- $\sigma_{q_1}^2 = \frac{\Delta^2}{12} \sum (2(\frac{1}{2})^n - (\frac{1}{4})^n) \approx 1.83 \frac{\Delta^2}{12}$
- $\sigma_{q_2}^2 = \frac{\Delta^2}{12} \sum (\frac{1}{4})^n \approx 1.07 \frac{\Delta^2}{12}$

Total $2.90 \frac{\Delta^2}{12}$

Statistical analysis of quantization effects

What is we interchange the 2 sections? Is the output quantization noise power A: larger? B: smaller? C: equal?

$$H(z) = H_1(z)H_2(z) = H_2(z)H_1(z)$$



Statistical analysis of quantization effects

Practice:

- Exercise 9.32
- Exercise 9.34
- Exercise 9.38