

## Resit exam EE2S11 SIGNALS & SYSTEMS

July 19, 2021

### Block 1 (13:30-15:00)

Open book, strictly timed take-home exam. (Electronic) copies of the book and the course slides allowed. No other tools except a basic pocket calculator permitted.

Upload answers during 14:55–15:10

This block consists of three questions (25 points); more than usual, and this will be taken into account during grading. Answer in Dutch or English. Make clear in your answer how you reach the final result; the road to the answer is very important. Write your name and student number on each sheet.

#### Question 1 (11 points)

Given a causal time-domain signal  $i(t)$ . On its ROC, the one-sided Laplace transform of  $i(t)$  is given by

$$I(s) = \frac{s - 2}{s^2 + 2s + 2}.$$

- (a) What is its ROC?
- (b) Determine  $i(0^+)$ .
- (c) Determine  $i(t)$ .
- (d) Compute  $\frac{di}{dt}$ .
- (e) Determine the inverse Laplace transform of

$$U(s) = \frac{s^2 - 2s}{s^2 + 2s + 2},$$

which has the same ROC as  $I(s)$ .

#### Question 2 (5 points)

Given the signal  $x(t) = te^{-\alpha t}u(t)$  with  $\alpha > 0$ .

- (a) Determine the convolution  $y(t) = x(t) * x(t)$  directly using the convolution integral.
- (b) Determine the convolution  $y(t) = x(t) * x(t)$  using the Laplace transform.

#### Question 3 (9 points)

A periodic signal  $x(t)$  with a fundamental period  $T_0$  has a Fourier series expansion

$$x(t) = \sum_{k=-\infty}^{\infty} \frac{\alpha}{\beta + (k\pi)^2} e^{jk\pi t} \quad \text{with } \alpha > 0 \text{ and } \beta > 0.$$

- (a) What is the fundamental period  $T_0$ ?
- (b) What is the average value of  $x(t)$ ?
- (d) Is  $x(t)$  even, odd, or neither? Motivate your answer.

One of the harmonics of  $x(t)$  is expressed as  $a \cos(4\pi t)$ .

- (d) What is  $a$ ?

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Block 2 (15:25-16:55)

Open book, strictly timed take-home exam. (Electronic) copies of the book and the course slides allowed. No other tools except a basic pocket calculator permitted.

Upload answers during 16:50–17:05

This block consists of four questions (25 points); more than usual, and this will be taken into account during grading. Answer in Dutch or English. Make clear in your answer how you reach the final result; the road to the answer is very important. Write your name and student number on each sheet.

### Question 4 (9 points)

- (a) Given the signals  $x[n] = [\dots, 0, 1, 2, \boxed{3}, 0, 0, \dots]$  and  $h[n] = [\dots, \boxed{0}, 2, 1, 0, \dots]$ , where the ‘box’ denotes the value for  $n = 0$ .

Determine  $y[n] = h[n] * x[n]$  using the convolution sum.

- (b) Given an input signal  $x[n] = (\frac{1}{3})^{|n|}$ . Determine the  $z$ -transform  $X(z)$ , also specify the ROC.

- (c) Let  $h[n] = (\frac{1}{2})^n u[n]$  be the impulse response of a filter, let

$$Y(z) = \frac{2z^2}{2z^2 + z - 1}, \quad \text{ROC: } |z| > 1,$$

and let  $y[n]$  be the corresponding signal.

Compute the input signal  $x[n]$  for which this  $y[n]$  is the output of the filter.

- (d) A filter  $H(z)$  is called *allpass* if its magnitude response (amplitude spectrum) is constant over frequency.

Consider

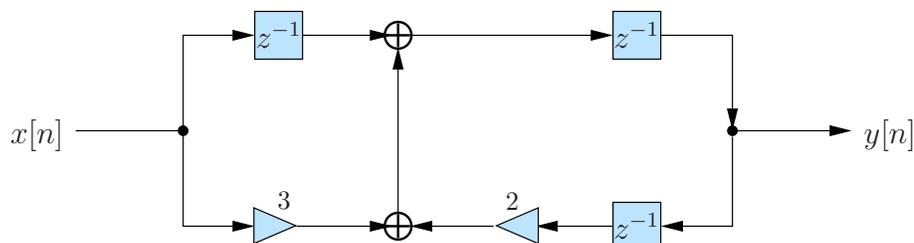
$$H(z) = z^{-1} \frac{1 + 3z^{-2}}{3 + z^{-2}}, \quad \text{ROC: } |z| > \frac{1}{\sqrt{3}}$$

Determine if  $H(z)$  is an allpass filter.

- (e) Compute all poles and zeros of  $H(z)$  in (d) and draw a pole-zero plot.

### Question 5 (5 points)

Consider the following system realization:

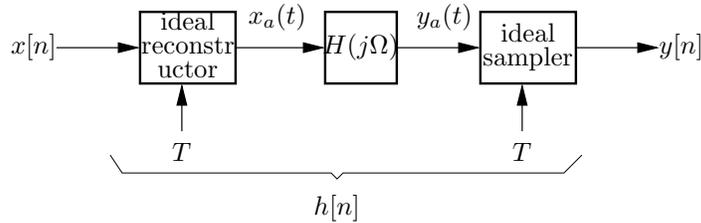


- (a) Determine the transfer function  $H(z)$ .
- (b) Is this a minimal realization? (Why?)
- (c) Draw the corresponding Direct Form no. 2 realization.
- (d) Determine  $h[1]$ , the impulse response at time  $n = 1$ .

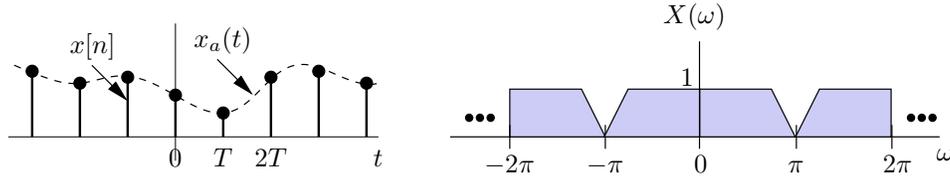
**Question 6 (6 points)**

We have a discrete time sequence  $x[n]$ , and wish to implement a delay:  $y[n] = x[n - \Delta]$ . If  $\Delta$  is not an integer, this has no formal meaning as we cannot shift the sequence  $x[n]$  by anything but an integer.

To implement the effect of a non-integer delay, we consider the following setup:



The signal is first reconstructed (D/A conversion including an ideal reconstruction filter) assuming a certain sampling period of  $T$ , resulting in  $x_a(t)$ . Next, a suitable continuous-time filter  $H(j\Omega)$  is applied, and the resulting signal  $y_a(t)$  is sampled again with period  $T$  so that we obtain the series  $y[n] = y_a(nT)$ .



- (a) The spectrum  $X(\omega)$  corresponding to  $x[n]$  is drawn schematically above. Sketch the spectrum  $X_a(\Omega)$  after ideal reconstruction. (Also indicate values on the horizontal and vertical axes.)
- (b) Express  $x_a(t)$  in terms of  $x[n]$ .
- (c) Relate  $y_a(t)$  to  $x_a(t)$  in an equation.  
Based on this, specify  $H(j\Omega)$  such that the desired delay is obtained.
- (d) Express  $y[n]$  in terms of  $x[n]$  in an equation.  
Based on this, specify the equivalent discrete-time filter  $h[n]$  that implements the non-integer delay.
- (e) How should  $T$  be selected?

**Question 7 (5 points)**

We use the bilinear transform to design a digital lowpass filter  $H(z)$  with the following specifications:

- Passband:  $0 \leq |\omega| \leq 0.25\pi$ , maximal ripple 0.5 dB
  - Stopband:  $0.4\pi \leq |\omega| \leq \pi$ , minimal damping 50 dB.
- (a) Specify the passband and stopband frequencies for the design of the corresponding analog lowpass filter
- (b) What is the required filter order if we use a Butterworth filter?
- (c) Suppose  $G(z) = H(-z)$ . Give a plot of the magnitude response  $|G(e^{j\omega})|$ . Also specify values on both axes (derived from the specifications of  $H(z)$ ).