

**Exam EE2S11 Signals and Systems**  
**Resit on complete course: 25 juli 2016, 13:30–16:30**

Closed book; one double-sided A4 page of handwritten notes permitted

This exam consists of seven questions (45 points)

**Question 1 (4 points)**

Which of the following statements are true? (Just provide the answers, no motivation necessary.)

- a) If  $x(t)$  is a causal signal, the Region of Convergence (ROC) of its Laplace transform lies to the right of a line through the rightmost singularity.
- b) If  $x(t)$  is an anti-causal signal, the ROC of its Laplace transform lies to the left of a line through the leftmost singularity.
- c) If  $x(t)$  is a noncausal signal and its Laplace transform exists, then its ROC is a strip in the  $s$ -plane parallel to the imaginary axis.
- d) The ROC does not contain any singularities.

**Solution:**

All statements are true.

**Question 2 (8 points)**

Determine the inverse Laplace transform of the following functions:

- a)  $X(s) = \frac{2s + 1}{s^2 + 9}$ , ROC:  $\text{Re}(s) > 0$
- b)  $Y(s) = \frac{s^2 + 2}{s^3 - s}$ , ROC:  $\text{Re}(s) > 1$
- c)  $Z(s) = \frac{2}{s^2(s - 1)}$ , ROC:  $\text{Re}(s) > 1$

**Solution:**

a)

$$X(s) = 2\frac{s}{s^2 + 9} + \frac{1}{3}\frac{3}{s^2 + 9} \quad \text{Re}(s) > 0.$$

An inverse Laplace transform gives  $x(t) = [2\cos(3t) + \frac{1}{3}\sin(3t)]u(t)$ .

b) Since  $s^3 - s = s(s + 1)(s - 1)$ , we have

$$Y(s) = \frac{s^2 + 2}{s(s + 1)(s - 1)} = -2\frac{1}{s} + \frac{3}{2}\frac{1}{s - 1} + \frac{3}{2}\frac{1}{s + 1} \quad \text{Re}(s) > 1.$$

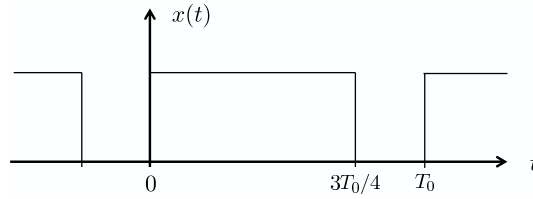
An inverse Laplace transform gives  $y(t) = (-2 + \frac{3}{2}e^t + \frac{3}{2}e^{-t})u(t)$ .

c) We have

$$Z(s) = -2\frac{1}{s^2} - 2\frac{1}{s} + 2\frac{1}{s - 1} \quad \text{Re}(s) > 1.$$

An inverse Laplace transform gives  $z(t) = 2(e^t - t - 1)u(t)$ .

**Question 3 (8 points)**



Consider the  $T_0$ -periodic signal  $x(t)$  as depicted above. The Fourier series of  $x(t)$  can be expressed as

$$x(t) = c_0 + 2 \sum_{k=1}^{\infty} (c_k \cos(k\Omega_0 t) + d_k \sin(k\Omega_0 t)), \quad \Omega_0 = \frac{2\pi}{T_0},$$

where the coefficients  $c_k$  and  $d_k$  are given by

$$c_k = \frac{1}{T_0} \int_{t_0}^{t_0+T_0} x(t) \cos(k\Omega_0 t) dt, \quad d_k = \frac{1}{T_0} \int_{t_0}^{t_0+T_0} x(t) \sin(k\Omega_0 t) dt, \quad k = 0, 1, 2, \dots$$

- Compute the Fourier coefficients  $c_k$  and  $d_k$ .
- The decay of the Fourier coefficients is  $\mathcal{O}(1/k)$ . Explain why this is the case.
- What would be the effect on the Fourier coefficients  $c_k$  and  $d_k$  if we raise the signal  $x(t)$  by a constant  $c \in \mathbb{R}$ ? That is, if we consider the signal  $x(t) + c$ .
- What would be the effect on the Fourier coefficients  $c_k$  and  $d_k$  if we shift the signal  $x(t)$  by a constant  $c \in \mathbb{R}$ ? That is, if we consider the signal  $x(t - c)$ .
- Considering the shifted signal of item d), for what values of  $c$  do the coefficients  $c_k$  and/or  $d_k$  vanish? Motivate your answer.

**Solution:**

- a)  $c_0$  is given by

$$c_0 = \frac{1}{T_0} \int_0^{3T_0/4} dt = 3/4.$$

For  $k = 1, 2, \dots$  we have

$$\begin{aligned} c_k &= \frac{1}{T_0} \int_0^{3T_0/4} \cos(k\Omega_0 t) dt = \frac{1}{2\pi k} \sin(k\Omega_0 t) \Big|_0^{3T_0/4} \\ &= \frac{1}{2\pi k} \sin(k3\pi/2), \end{aligned}$$

and

$$\begin{aligned} d_k &= \frac{1}{T_0} \int_0^{3T_0/4} \sin(k\Omega_0 t) dt = \frac{-1}{2\pi k} \cos(k\Omega_0 t) \Big|_0^{3T_0/4} \\ &= \frac{1}{2\pi k} (1 - \cos(k3\pi/2)). \end{aligned}$$

- The decay of the Fourier coefficients is  $\mathcal{O}(1/k)$  because the signal is not continuous.
- An offset  $c$  will only affect  $c_0$ , which represents the mean value. Hence  $c'_0 = c_0 + c$  and all the other  $c_k$ 's and  $d_k$ 's remain the same.

d) The value  $c_0$  will not change. For the other  $c_k$ 's and  $d_k$ 's we find

$$c'_k = \frac{1}{T_0} \int_c^{3T_0/4+c} \cos(k\Omega_0 t) dt = \frac{1}{2\pi k} (\sin(k\Omega_0(3T_0/4 + c)) - \sin(k\Omega_0 c)),$$

$$d'_k = \frac{1}{T_0} \int_c^{3T_0/4+c} \sin(k\Omega_0 t) dt = \frac{1}{2\pi k} (\cos(k\Omega_0 c) - \cos(k\Omega_0(3T_0/4 + c))).$$

e) The coefficients  $d_k$  will vanish when the shifted function is even symmetric. This happens for  $c = T_0/8 \bmod T$  and  $c = -3T_0/8 \bmod T$ . Since we can't make the shifted function oddly symmetric, we can't make all  $c_k$ 's zeros.

#### Question 4 (10 points)

Determine the  $z$ -transform for the following discrete-time signals, also specify the ROC:

a)  $x[n] = u[n] + \left(\frac{1}{2}\right)^n u[n - 2],$

b)  $x[n] = 2 \sin\left(\frac{\pi}{6}n\right)u[-n].$

Determine the signals  $x[n]$  corresponding to the  $z$ -transforms:

c)  $X(z) = (1 - z^{-1})^2, \quad \text{ROC: } z \neq 0.$

d)  $X(z) = \frac{1.2}{(1 - z^{-1})(1 + 0.2z^{-1})}, \quad \text{ROC: } 0.2 < |z| < 1.$

Determine the frequency response  $H(e^{j\omega})$  for the system defined by the difference equation:

e)  $y[n] = 0.5y[n - 1] + x[n] + x[n - 1], \quad n \geq 0.$

**Solution:**

a) First rewrite the second term as  $\left(\frac{1}{2}\right)^2 \left(\frac{1}{2}\right)^{n-2} u[n - 2]$ , so that we can use the shift property of the  $z$ -transform. It follows that

$$X(z) = \frac{1}{1 - z^{-1}} + \frac{1}{4} \frac{z^{-2}}{1 - \left(\frac{1}{2}\right)z^{-1}}, \quad \text{ROC: } |z| > 1.$$

b) Use the property  $\sin(\omega_0 n)u(n) \Leftrightarrow \frac{\sin(\omega_0)z^{-1}}{1 - 2\cos(\omega_0)z^{-1} + z^{-2}}$  (ROC:  $|z| > 1$ ).

We also need to use  $x[-n] \Leftrightarrow X(z^{-1})$  and note that  $\sin(\omega_0 n) = -\sin(-\omega_0 n)$ .

It follows that

$$X(z) = \frac{-z}{1 - \sqrt{3}z + z^2} \quad \text{ROC: } |z| < 1.$$

c)  $X(z) = (1 - z^{-1})^2 = 1 - 2z^{-1} + z^{-2}$ . Hence

$$x[n] = \delta[n] - 2\delta[n - 1] + \delta[n - 2].$$

d) Partial fraction expansion gives

$$X(z) = \frac{1}{1 - z^{-1}} + \frac{0.2}{1 + 0.2z^{-1}}.$$

Inspecting the ROC, we see that the first term will give an anti-causal signal and the second term will become causal. We therefore write

$$X(z) = \frac{-z}{1-z} + \frac{0.2}{1+0.2z^{-1}}.$$

Applying the inverse transform gives

$$x[n] = -u[-n-1] + 0.2(-0.2)^n u[n].$$

e) We first determine  $H(z)$  as

$$H(z) = \frac{1+z^{-1}}{1-\frac{1}{2}z^{-1}}.$$

Therefore, the frequency response is

$$H(e^{j\omega}) = \frac{1+e^{-j\omega}}{1-\frac{1}{2}e^{-j\omega}}.$$

### Question 5 (4 points)

A continuous-time signal  $x_a(t)$  has a Fourier transform  $X_a(\Omega) = u(\Omega+1) - u(\Omega-1)$ .

- Determine  $x_a(t)$ .
- What is the largest value of the sampling period  $T_s$  that would not cause aliasing when sampling  $x_a(t)$ ?
- We sample the signal at  $T_s = \pi$ . Draw the sampled signal  $x[n]$  (also specify the values on the axes).

**Solution:**

a) Table on p.383 (with  $\Omega_0 = 1$ ):

$$x_a(t) = \frac{\sin(t)}{\pi t}$$

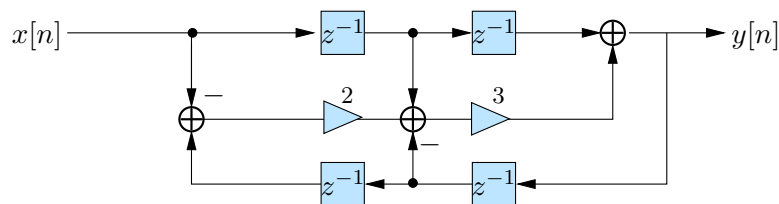
b) The signal is bandlimited with bandwidth  $\Omega_{\max} = 1$ , or  $F_{\max} = 1/(2\pi)$ . Therefore, we have to sample at Nyquist rate  $F_s = 2F_{\max} = 1/\pi$ . The corresponding sampling period is  $T_s = \pi$ .

c) In this case we sample the sin-function exactly at its zeros. Therefore

$$x[n] = \frac{1}{\pi} \delta[n]$$

### Question 6 (4 points)

Consider the following system realization:



- Determine the transfer function  $H(z)$ .
- Is this a stable system? (Why?)
- Is this a minimal realization? (Why?)

**Solution:**

- a) Introduce additional variables  $P(z) = z^{-1}X(z)$  at the output of the first delay, and  $Q(z) = z^{-1}Y(z)$  at the output of the delay in the bottom branch. The equation for  $Y(z)$  is

$$Y = z^{-1}P + 3(P + 2(z^{-1}Q - X) - Q)$$

Substitute  $P(z)$  and  $Q(z)$  to obtain

$$Y = z^{-2}X + 3(z^{-1}X + 2(z^{-2}Y - X) - z^{-1}Y)$$

$$(1 + 3z^{-1} - 6z^{-2})Y = (-6 + 3z^{-1} + z^{-2})X$$

The transfer function is

$$H(z) = \frac{-6 + 3z^{-1} + z^{-2}}{1 + 3z^{-1} - 6z^{-2}}$$

(This shows that it is a 2nd order allpass function.)

- b) The poles are  $z = -1\frac{1}{2} \pm j\frac{1}{2}\sqrt{15}$ . Clearly the poles are outside the unit circle: unstable.  
 c) Not minimal because 4 delays are used and  $H(z)$  is 2nd order.

**Question 7 (7 points)**

A second-order analog lowpass filter (Butterworth filter) has transfer function

$$G_a(s) = \frac{1}{s^2 + \sqrt{2}s + 1}$$

The 3-dB cut-off frequency of this filter is  $\Omega_c = 1$  rad/s.

Using the bilinear transform and the above filter as a template, we will now design a digital *high*-pass filter  $H(z)$  with cut-off frequency  $\omega'_c = \frac{2}{3}\pi$ .

- a) What should be the corresponding cut-off frequency in the analog frequency domain?  
 b) Which frequency transformation should be used?  
 c) What is  $H_a(s)$ ?  
 d) What is  $H(z)$ ?  
 e) Verify that the design meets the specifications.

**Solution:**

- a) The bilinear transform gives  $\Omega'_c = \tan(\frac{1}{2}\omega'_c) = \tan(\frac{1}{3}\pi) = \sqrt{3}$ .  
 b)  $\Omega \rightarrow \frac{\sqrt{3}}{\Omega}$ . This transforms lowpass into highpass, with cutoff at  $\sqrt{3}$ .  
 c) Likewise  $s \rightarrow \frac{\sqrt{3}}{s}$ . This gives

$$H_a(s) = \frac{1}{\frac{3}{s^2} + \sqrt{6}s + 1} = \frac{s^2}{s^2 + \sqrt{6}s + 3}$$

d) Apply the bilinear transform:  $s \rightarrow \frac{1 - z^{-1}}{1 + z^{-1}}$ . This gives

$$H(z) = \frac{(1 - z^{-1})^2}{(1 - z^{-1})^2 + \sqrt{6}(1 - z^{-1})(1 + z^{-1}) + 3(1 + z^{-1})^2} = \dots$$

e) We evaluate at  $\omega = 0$ ,  $\omega = \pi$  and  $\omega = \omega_c$ :

$$\begin{aligned} H(z = e^{j0}) &= 0 \\ H(z = e^{j\pi}) &= \frac{2^2}{2^2 + 0 + 0} = 1 \\ H(z = e^{j2\pi/3}) &= H(z = \frac{1}{2} + \frac{1}{2}\sqrt{3}j) = H_a(s = j\sqrt{3}) = \frac{-3}{-3 + j\sqrt{6 \cdot 3} + 3} = j\frac{1}{\sqrt{2}} \end{aligned}$$

This shows that indeed  $H(z)$  is a highpass filter with -3 dB point at  $\omega_c$ .