

# Exercises Ch.10 z-transform

Exercise 1 – exercises taken from Chaparro (first edition)

## Mapping of $s$ -plane into the $z$ -plane

The poles of the Laplace transform  $X(s)$  of an analog signal  $x(t)$  are

$$p_{1,2} = -1 \pm j1$$

$$p_3 = 0$$

$$p_{4,5} = \pm j1$$

There are no zeros. If we use the transformation  $z = e^{sT_s}$  with  $T_s = 1$ :

- (a) Determine where the given poles are mapped into the  $z$ -plane.
- (b) How would you determine if these poles are mapped inside, on, or outside the unit circle in the  $z$ -plane? Explain.
- (c) Carefully plot the poles and the zeros of the analog and the discrete-time signals in the Laplace and the  $z$ -planes.

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answer

**Pr 9.1** (a)(c) For  $T_s = 1$  the transformation from the s-plane to the z-plane  $z = e^s$  is such that for  $s = \sigma + j\Omega$

$$z = e^\sigma e^{j\Omega}$$

For  $s = -1 \pm j1$ , the poles of the analog system, the corresponding singularities in the z-plane are given by

$$z = e^{-1} e^{\pm j1}$$

which are inside the unit disk as  $e^{-1} < 1$  with a radian frequency of  $\pm 1$

The pole  $s = 0$  is mapped into  $z = e^0 = 1$ , and the poles  $s = \pm j1$  are mapped into  $z = 1e^{\pm j1}$  with unit magnitude and radian frequencies  $\pm 1$ .

(b) By expressing  $z = re^{j\omega} = e^\sigma e^{j\Omega}$  for  $T_s = 1$ , the radius is given by  $r = e^\sigma$  so that if  $\sigma < 0$  the singularities are inside the unit circle, if  $\sigma = 0$  they are on the unit circle, and if  $\sigma > 0$  they are outside the unit circle.

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## Exercise 2

### Mapping of $z$ -plane into the $s$ -plane

Consider the inverse relation given by  $z = e^{sT_s}$ —that is, how to map the  $z$ -plane into the  $s$ -plane.

- (a) Find an expression for  $s$  in terms of  $z$  from the relation  $z = e^{sT_s}$ .
- (b) Consider the mapping of the unit circle (i.e.,  $z = 1e^{j\omega}$ ,  $-\pi \leq \omega < \pi$ ). Obtain the segment in the  $s$ -plane resulting from the mapping.
- (c) Consider the mapping of the inside and the outside of the unit circle. Determine the regions in the  $s$ -plane resulting from the mappings.
- (d) From the above results, indicate the region in the  $s$ -plane to which the whole  $z$ -plane is mapped into. Since  $\omega = \omega + 2\pi$ , is this mapping unique? Explain.

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answer

**Pr 9.2** (a) Solving for  $s$  in the given relation we obtain

$$s = \log(z)/T_s.$$

(b) Points on the unit circle that in the  $z$ -plane are represented by  $z = 1e^{j\omega}$  (unit radius and frequency  $-\pi \leq \omega < \pi$ ) will be mapped into

$$s = \frac{\log(1e^{j\omega})}{T_s} = \frac{0 + j\omega}{T_s} = j \frac{\omega}{T_s} = j\Omega$$

or points in the  $j\Omega$  axis of the  $s$ -plane. For instance  $z = 1 = 1e^{j0}$  is mapped into  $s = j0$ , the origin of the  $s$ -plane;  $z = 1e^{\pm j\pi/2}$  is mapped into  $s = \pm j\pi/(2T_s)$  and  $z = -1 = 1e^{\pm j\pi}$  maps into  $s = \pm j\pi/T_s$ . Thus, the unit disk is mapped into a line in the  $j\Omega$ -axis from  $-\pi/T_s$  to  $\pi/T_s$ .

(c) In general,  $z = re^{j\omega}$  is mapped into

$$s = \frac{\log[re^{j\omega}]}{T_s} = \underbrace{\frac{\log[r]}{T_s}}_{\sigma} + j \underbrace{\frac{\omega}{T_s}}_{\Omega}$$

where we used  $r = e^{\sigma T_s}$  and  $\omega = \Omega T_s$  giving us the correct expression for  $s = \sigma + j\Omega$ . The outside of the unit circle, i.e.,  $r > 1$  maps into the right-hand strip defined by  $\sigma > 0$  and  $-\pi/T_s \leq \Omega < \pi/T_s$ , the inside of the unit circle, i.e.,  $r \leq 1$  maps into the left-hand strip defined by  $\sigma < 0$  and  $-\pi/T_s \leq \Omega < \pi/T_s$ .

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answer

(d) The above shows that the z-plane is mapped into the strip between  $-\pi/T_s$  and  $\pi/T_s$  for all  $\sigma$  in the s-plane. Adding  $2\pi k$ , multiples of  $2\pi$ , the discrete frequencies remain the same, i.e.,  $\omega = \omega + 2\pi k$  for  $k = 0, \pm 1, \pm 2, \dots$ . The mapping of the z-plane with these frequencies gives the same values of  $\sigma$  as before, but the analog frequencies will be the mapping of  $(2k - 1)\pi \leq \omega < (2k + 1)\pi$ :

$$\frac{(2k - 1)\pi}{T_s} \leq \Omega < \frac{(2k + 1)\pi}{T_s}$$

corresponding to strips of width  $2\pi/T_s$  above (for  $k \geq 1$ ) and below (for  $k \leq -1$ ) the one we considered before. Thus, the z-plane is mapped separately into strips of the same width in the s-plane.

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## Exercise 3

### Z-transform and ROCs

Consider the noncausal sequence

$$s[n] = s_1[n] + s_2[n]$$

where  $s_1[n] = u[n]$  is causal and  $s_2[n] = -u[-n]$  is anti-causal. This signal is the signum, or sign function, that extracts the sign of a real-valued signal—that is,

$$s[n] = \text{sgn}(x[n]) = \begin{cases} -1 & x[n] < 0 \\ 0 & x[n] = 0 \\ 1 & x[n] > 0 \end{cases}$$

- (a) Find the Z-transforms of  $s_1[n]$  and  $s_2[n]$ , indicating the corresponding ROC.
- (b) Determine the Z-transform  $S(z)$ .

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answer

**Pr 9.3** (a) The Z-transform of  $s_1[n]$  is

$$S_1(z) = \sum_{n=0}^{\infty} z^{-n} = \frac{1}{1 - z^{-1}}$$

provided that  $|z^{-1}| < 1$ , thus  $|z| > 1$  is the region of convergence for  $S_1(z)$ . The Z-transform of  $s_2[n]$  is given by

$$S_2(z) = - \sum_{n=-\infty}^0 z^{-n} = - \sum_{m=0}^{\infty} z^m = \frac{-1}{1 - z}$$

where the last sum converges for  $|z| < 1$ .

(b) The condition for

$$S(z) = S_1(z) + S_2(z) = \frac{1}{1 - z^{-1}} - \frac{1}{1 - z} = \frac{1 + z^{-1}}{1 - z^{-1}}$$

to converge is that  $|z| > 1$  and that  $|z| < 1$  simultaneously, which is not possible. Since there is no region of convergence for  $S(z)$ , the Z-transform of  $s[n]$  does not exist.

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## Exercise 4

### Z-transform and ROC

Given the anti-causal signal

$$x[n] = -\alpha^n u[-n]$$

- (a) Determine the Z-transform  $X(z)$ , and carefully plot the ROC when  $\alpha = 0.5$  and  $\alpha = 2$ . For which of the two values of  $\alpha$  does  $X(e^{j\omega})$  exist?
- (b) Find the signal that corresponds to the derivative  $dX(z)/dz$ . Express it in terms of  $\alpha$ .



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answer

**Pr 9.4** (a) The signal  $x[n]$  can be written as

$$\begin{aligned}x[n] &= -\delta[n] - \alpha^{-1}\delta[n+1] - \alpha^{-2}\delta[n+2] - \dots \\ &= -\delta[n] - \frac{1}{\alpha}\delta[n+1] - \frac{1}{\alpha^2}\delta[n+2] - \dots\end{aligned}$$

So that its Z-transform is given by

$$\begin{aligned}X(z) &= -1 - \frac{z}{\alpha} - \frac{z^2}{\alpha^2} - \dots \\ &= -\sum_{n=0}^{\infty} \left(\frac{z}{\alpha}\right)^n = -\frac{1}{1-z/\alpha} = \frac{\alpha z^{-1}}{1-\alpha z^{-1}} \quad |z| < |\alpha|\end{aligned}$$

If  $\alpha = 0.5$ , the ROC is the interior of a circle of radius 0.5, which does not include the unit circle. The ROC in this case indicates that the signal is non-causal. If  $\alpha = 2$ , the ROC is the interior of a circle of radius 2, including the unit circle, and indicating the signal is non-causal. In this case  $X(e^{j\omega})$  is defined, but it is not when  $\alpha = 0.5$ .

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(b) Computing the derivative of  $X(z)$  with respect to  $z$  gives

$$\begin{aligned}\frac{d X(z)}{dz} &= -\frac{1}{\alpha} - \frac{2z}{\alpha^2} - \frac{3z^2}{\alpha^3} \cdots = -\sum_{n=1}^{\infty} n \frac{z^{n-1}}{\alpha^n} \\ &= \sum_{m=-\infty}^{-1} m \alpha^m z^{-(m+1)}\end{aligned}$$

by letting  $m = -n$  in the last sum. Letting now  $k = m + 1$  in the final sum we have

$$\frac{d X(z)}{dz} = \sum_{k=-\infty}^0 (k-1) \alpha^{(k-1)} z^{-k}$$

We thus have the pair

$$\frac{d X(z)}{dz} \Leftrightarrow (n-1) \alpha^{(n-1)} u[-n].$$

Writing  $X(z)$  in positive powers of  $z$ , i.e.,  $X(z) = \alpha/(z - \alpha)$  its derivative with respect to  $z$  is

$$\frac{d X(z)}{dz} = \frac{-\alpha}{(z - \alpha)^2}$$

so that we have

$$\frac{-\alpha}{(z - \alpha)^2} = \frac{-\alpha z^{-2}}{(1 - \alpha z^{-1})^2} \Leftrightarrow (n-1) \alpha^{(n-1)} u[-n].$$

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## Exercise 5

### Significance of ROC

Consider a causal signal  $x_1[n] = u[n]$  and an anti-causal signal  $x_2[n] = -u[-n - 1]$ .

- (a) Find the Z-transforms  $X_1(z)$  and  $X_2(z)$  and carefully plot their ROCs. If the ROCs are not included with the Z-transforms, would you be able to tell which is the correct inverse? Explain.
- (b) Determine if it is possible to find the Z-transform of  $x_1[n] + x_2[n]$ .

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answer

**Pr 9.5** (a) The Z-transform of  $x_1[n]$  is

$$X_1(z) = \frac{1}{1 - z^{-1}} \quad |z| > 1$$

Using

$$u[-n - 1] = \begin{cases} 1 & n \leq -1 \\ 0 & n \geq 0 \end{cases}$$

the Z-transform of  $x_2[n]$  is

$$\begin{aligned} X_2(z) &= - \sum_{n=-\infty}^{-1} z^{-n} \\ &= - \sum_{m=0}^{\infty} z^m + 1 \\ &= \frac{-1}{1 - z} + 1 \\ &= \frac{1}{1 - z^{-1}} \quad |z| < 1 \end{aligned}$$

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answer

where we changed the variable in the sum,  $m = -n$ , and started the sum at zero instead of 1, and added 1 so it would not change. For  $X_2(z)$  to exist, it is required that  $|z| < 1$ .

If we ignore the regions of convergence, we would then have that  $1/(1 - z^{-1})$  would be the Z-transform of two completely different signals,  $x_1[n]$  and  $x_2[n]$ , rendering the transformation as useless.

(b) For the Z-transform of  $x_1[n] + x_2[n]$  to exist, requires that its ROC be the intersection of those of  $X_1(z)$  and  $X_2(z)$ . The intersection of  $|z| < 1$  and  $|z| > 1$  is empty, so the Z-transform does not exist.

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## Exercise 6

### Laplace and Z-transforms of sampled signals

An analog pulse  $x(t) = u(t) - u(t - 1)$  is sampled using a sampling period  $T_s = 0.1$ .

- (a) Obtain the discrete-time signal  $x(nT_s) = x(t)|_{t=nT_s}$  and plot it as a function of  $nT_s$ .
- (b) If the sampled signal is represented as an analog signal as

$$x_s(t) = \sum_{n=0}^{N-1} x(nT_s)\delta(t - nT_s)$$

determine the value of  $N$  in the above equation.

- (c) Compute the Laplace transform of the sampled signal (i.e.,  $X_s(s) = \mathcal{L}[x_s(t)]$ ).
- (d) Determine the Z-transform of  $x(nT_s)$ , or  $X(z)$ .
- (e) Indicate how to transform  $X_s(s)$  into  $X(z)$

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**Pr 9.7** (a) If  $T_s = 0.1$  the discrete-time signal is

$$x(0.1n) = [u(t) - u(t - 1)] |_{t=0.1n} = \begin{cases} 1 & 0 \leq 0.1n \leq 1 \text{ or } 0 \leq n \leq 10 \\ 0 & \text{otherwise} \end{cases}$$

(b) Expressing  $x[n]$  as indicated, then  $N = 11$ .

(c) The Laplace transform of the sampled signal is

$$\begin{aligned} X_s(s) &= \sum_{n=0}^{10} \mathcal{L}[\delta(t - nT_s)] \\ &= \sum_{n=0}^{10} e^{-0.1ns} \\ &= \frac{1 - e^{-1.1s}}{1 - e^{-0.1s}} \end{aligned}$$

(d) The z-transform of the discrete-time signal is

$$X(z) = \sum_{n=0}^{10} z^{-n} = \frac{1 - z^{-11}}{1 - z^{-1}}$$

(e) To transform  $X_s(s)$  into  $X(z)$  we let  $z = e^{0.1s}$ .

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## Exercise 7

### Computation of Z-transform

A causal exponential  $x(t) = 2e^{-2t}u(t)$  is sampled using a sampling period  $T_s = 1$ . The corresponding discrete-time signal is  $x[n] = 2e^{-2n}u[n]$ .

- (a) Express the discrete-time signal as  $x[n] = 2\alpha^n u[n]$  and give the value of  $\alpha$ .
- (b) Find the Z-transform  $X(z)$  of  $x[n]$  and plot its poles and zeros in the  $z$ -plane.



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answer

**Pr 9.9** (a) The discrete-time signal  $x[n] = 2e^{-2n}u[n]$  can be equally written

$$x[n] = 2(e^{-2})^n = 2\alpha^n$$

or  $\alpha = e^{-2} < 1$ .

(b) The z-transform of  $x[n]$  is

$$\begin{aligned} X(z) &= \sum_{n=0}^{\infty} 2\alpha^n z^{-n} \\ &= \sum_{n=0}^{\infty} 2(\alpha z^{-1})^n \\ &= \frac{2}{1 - \alpha z^{-1}} \quad |\alpha z^{-1}| < 1 \quad \text{or} \quad |z| > |\alpha| \end{aligned}$$

To find poles and zeros let

$$X(z) = \frac{2z}{z - \alpha}$$

with zero  $z = 0$  and pole  $z = \alpha$ .

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## Exercise 8

### Computation of Z-transform

Consider the signal  $x[n] = 0.5(1 + [-1]^n)u[n]$ .

- (a) Plot  $x[n]$  and use the definition of the Z-transform to obtain its Z-transform,  $X(z)$ .
- (b) Use the linearity property and the Z-transforms of  $u[n]$  and  $[-1]^n u[n]$  to find the Z-transform  $X(z) = \mathcal{Z}[x[n]]$ .
- (c) Determine and plot the poles and the zeros of  $X(z)$ .

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answer

**Pr 9.10** (a) The given signal can also be written

$$x[n] = \begin{cases} 1 & n \geq 0 \text{ and even} \\ 0 & \text{otherwise} \end{cases}$$

(b) Using the above expression for  $x[n]$ , we have

$$\begin{aligned} X(z) &= \sum_{n=0, \text{ even}}^{\infty} 1 z^{-n} \\ &= \sum_{m=0}^{\infty} 1 z^{-2m} = \frac{1}{1 - z^{-2}} \quad |z| > 1 \end{aligned}$$

where we let  $n = 2m$  to find the final expression.

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answer

(c) The z-transform of  $x[n]$  is also obtained by using its linearity

$$\begin{aligned} X(z) &= 0.5\mathcal{Z}[u[n]] + 0.5\mathcal{Z}[(-1)^n u[n]] \\ &= \frac{1}{2(1-z^{-1})} + 0.5 \sum_{n=0}^{\infty} (-z^{-1})^n \\ &= \frac{1}{2(1-z^{-1})} + \frac{1}{2(1+z^{-1})} \\ &= \frac{1}{1-z^{-2}} \quad |z^{-1}| < 1 \quad \text{or} \quad |z| > 1 \end{aligned}$$

(c) To find the poles and zeros let

$$X(z) = \frac{z^2}{z^2 - 1}$$

with poles  $z = \pm 1$ , and zeros  $z = 0$ , double.

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## Exercise 9

### Solution of difference equations with Z-transform

Consider a system represented by the first-order difference equation

$$y[n] = x[n] - 0.5y[n - 1]$$

where  $y[n]$  is the output and  $x[n]$  is the input.

- (a) Find the Z-transform  $Y(z)$  in terms of  $X(z)$  and the initial condition  $y[-1]$ .
- (b) Find an input  $x[n] \neq 0$  and an initial condition  $y[-1] \neq 0$  so that the output is  $y[n] = 0$  for  $n \geq 0$ . Verify you get this result by solving the difference equation recursively.
- (c) For zero initial conditions, find the input  $x[n]$  so that  $y[n] = \delta[n] + 0.5\delta[n - 1]$ .

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**Pr 9.11** (a) The Z-transform of the difference equation

$$y[n] = x[n] - 0.5y[n - 1] \quad n \geq 0$$

with initial condition  $y[-1]$  is

$$Y(z) = X(z) - 0.5(z^{-1}Y(z) + y[-1])$$

so that

$$Y(z) = \frac{X(z)}{1 + 0.5z^{-1}} - \frac{0.5y[-1]}{1 + 0.5z^{-1}}$$

(b) If  $X(z) = 1$ ,  $y[-1] = 2$  then  $Y(z) = 0$  and therefore  $y[n] = 0$  for  $n \geq 0$  but  $y[-1] = 2$ .

If  $X(z) = 1$  or  $x[n] = \delta[n]$  and  $y[-1] = 2$  the difference equation is

$$y[n] = \delta[n] - 0.5y[n - 1] \quad n \geq 0$$

and can be solved recursively

$$y[0] = 1 - 0.5 \times 2 = 0$$

$$y[1] = 0 - 0.5 \times 0 = 0$$

$$y[2] = 0 - 0.5 \times 0 = 0$$

$\vdots$

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answer

(c) If  $y[-1] = 0$  and  $x[n] = \delta[n]$  then we can compute  $y[n] = h[n]$ , i.e., the impulse response. The corresponding transfer function is then from the equation for  $Y(z)$ :

$$H(z) = \mathcal{Z}[h[n]] = \frac{Y(z)}{X(z)} = \frac{1}{1 + 0.5z^{-1}}$$

If we want  $y[n] = \delta[n] + 0.5\delta[n - 1]$  or  $Y(z) = 1 + 0.5z^{-1}$  then

$$X(z) = \frac{Y(z)}{H(z)} = (1 + 0.5z^{-1})^2 = 1 + z^{-1} + 0.25z^{-2}$$

which gives  $x[n] = \delta[n] + \delta[n - 1] + 0.25\delta[n - 2]$

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## Exercise 10

### Inverse Z-transform and poles and zeros

When finding the inverse Z-transform of functions with  $z^{-1}$  terms in the numerator, the fact that  $z^{-1}$  can be thought of as a delay operator can be used to simplify the computation. Consider

$$X(z) = \frac{1 - z^{-10}}{1 - z^{-1}}$$

- (a) Use the Z-transform of  $u[n]$  and the properties of the Z-transform to find  $x[n]$ .
- (b) If we consider  $X(z)$  a polynomial in negative powers of  $z$ , what would be its degree and the values of its coefficients?
- (c) Find the poles and the zeros of  $X(z)$  and plot them on the  $z$ -plane. Is there a pole or zero at  $z = 1$ ? Explain.



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answer

**Pr 9.14** (a) Writing  $X(z)$  as

$$X(z) = \frac{1}{1 - z^{-1}} - \frac{z^{-10}}{1 - z^{-1}}$$

since the inverse Z-transform of the first term is  $u[n]$ , then the inverse of the second is  $-u[n - 10]$  given that  $z^{-10}$  indicates a delay of 10 samples. Thus,

$$x[n] = u[n] - u[n - 10] = \begin{cases} 1 & 0 \leq n \leq 9 \\ 0 & \text{otherwise} \end{cases}$$

(b) Although  $X(z)$  has been shown as a ratio of two polynomials, using the above representation of  $x[n]$  its Z-transform is

$$X(z) = 1 + z^{-1} + \dots + z^{-9}$$

i.e., a 9<sup>th</sup>-order polynomial in  $z^{-1}$ .

(c) We can rewrite  $X(z)$  as

$$X(z) = \frac{z^{10} - 1}{z^9(z - 1)} = \frac{(z - 1) \prod_{k=1}^9 (z - e^{j\pi k/5})}{z^9(z - 1)} = \frac{\prod_{k=1}^9 (z - e^{j\pi k/5})}{z^9}$$

which is obtained by finding that the zeros of  $X(z)$  are values  $z_k^{10} = 1$  or  $z_k = e^{j2\pi k/10}$  for  $k = 0, \dots, 9$ . For  $k = 0$  the zero is  $z_0 = 1$ , which cancels the pole at 1.

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## Exercise 11

### Initial conditions and impulse response

A second-order system has the difference equation

$$y[n] = 0.25y[n - 2] + x[n]$$

where  $x[n]$  is the input and  $y[n]$  is the output.

- (a) Find the input  $x[n]$  so that for zero initial conditions, the output is given as  $y[n] = 0.5^n u[n]$ .
- (b) If  $x[n] = \delta[n] + 0.5\delta[n - 1]$  is the input to the above difference equation, find the impulse response of the system.

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**Pr 9.16** (a) For zero initial conditions we want

$$Y(z) = \frac{X(z)}{1 - 0.25z^{-2}} = \frac{1}{1 - 0.5z^{-1}}$$

which gives that

$$X(z) = 1 + 0.5z^{-1} \Rightarrow x[n] = \delta[n] + 0.5\delta[n - 1]$$

(b) For  $x[n] = \delta[n] + 0.5\delta[n - 1]$  we get  $Y(z) = H(z)(1 + 0.5z^{-1})$  which from the difference equation is equal to

$$Y(z) = \frac{1 + 0.5z^{-1}}{1 - 0.25z^{-2}}$$

so that when comparing them we find that

$$H(z) = \frac{1 + 0.5z^{-1}}{(1 + 0.5z^{-1})(1 - 0.25z^{-2})} = \frac{1}{1 - 0.25z^{-2}} = \frac{1}{(1 - 0.5z^{-1})(1 + 0.5z^{-1})}$$

with poles at  $\pm 0.5$  so that

$$H(z) = \frac{A}{1 + 0.5z^{-1}} + \frac{B}{1 - 0.5z^{-1}}$$

where

$$\begin{aligned} A &= \frac{1}{1 - 0.5z^{-1}} \Big|_{z^{-1}=-2} = 0.5 \\ B &= \frac{1}{1 + 0.5z^{-1}} \Big|_{z^{-1}=2} = 0.5 \end{aligned}$$

so that

$$h[n] = 0.5(-0.5)^n u[n] + 0.5^{n+1} u[n]$$

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## Exercise 12

### Convolution sum and product of polynomials

The convolution sum is a fast way to find the coefficients of the polynomial resulting from the multiplication of two polynomials.

- (a) Suppose  $x[n] = u[n] - u[n - 3]$ . Find its Z-transform  $X(z)$ , a second-order polynomial in  $z^{-1}$ .
- (b) Multiply  $X(z)$  by itself to get a new polynomial  $Y(z) = X(z)X(z) = X^2(z)$ . Find  $Y(z)$ .
- (c) Graphically show the convolution of  $x[n]$  with itself and verify that the result coincides with the coefficients of  $Y(z)$ .

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answer

**Pr 9.17** (a) The signal  $x[n] = \delta[n] + \delta[n - 1] + \delta[n - 2]$  has a Z-transform

$$X(z) = 1 + z^{-1} + z^{-2}$$

(b) Then

$$Y(z) = X^2(z) = (1 + z^{-1} + z^{-2})^2 = 1 + 2z^{-1} + 3z^{-2} + 2z^{-3} + z^{-4}$$

The convolution of the coefficients of  $X(z)$ , or  $x[n]$ , with themselves gives the sequence

$$y[n] = \delta[n] + 2\delta[n - 1] + 3\delta[n - 2] + 2\delta[n - 3] + \delta[n - 4]$$

The length of  $y[n]$  is twice that of  $x[n]$  minus one, or  $2 \times 3 - 1 = 5$  so that  $Y(z)$  is a fourth -degree polynomial.

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Exercise 13

## Inverse Z-transform

Find the inverse Z-transform of

$$X(z) = \frac{8 - 4z^{-1}}{z^{-2} + 6z^{-1} + 8}$$

and determine  $x[n]$  as  $n \rightarrow \infty$ . Assume  $x[n]$  is causal.

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answer

**Pr 9.18** Writing  $X(z)$  using terms found in tables, its partial fraction expansion is

$$\begin{aligned}X(z) &= \frac{2 - z^{-1}}{2(1 + 0.25z^{-1})(1 + 0.5z^{-1})} \\ &= \frac{A}{1 + 0.25z^{-1}} + \frac{B}{1 + 0.5z^{-1}}\end{aligned}$$

corresponding to the poles at  $-0.25$  and  $-0.5$ . The coefficients of the expansion are

$$\begin{aligned}A &= \frac{2 - z^{-1}}{2(1 + 0.5z^{-1})} \Big|_{z^{-1}=-4} = -3 \\ B &= \frac{2 - z^{-1}}{2(1 + 0.25z^{-1})} \Big|_{z^{-1}=-2} = 4\end{aligned}$$

so that

$$X(z) = \frac{-3}{1 + 0.25z^{-1}} + \frac{4}{1 + 0.5z^{-1}}$$

and the inverse is

$$x[n] = [-3(-0.25)^n + 4(-0.5)^n]u[n]$$

and in the steady-state it is zero.

# Exercises Ch.10 z-transform

## Exercise 14

### Z-transform properties and inverse transform

Sometimes the partial fraction expansion is not needed in finding the inverse Z-transform—instead the properties of the transform can be used. Consider the function

$$F(z) = \frac{z + 1}{z^2(z - 1)}$$

- (a) Determine whether  $F(z)$  is a proper rational function as a function of  $z$  and of  $z^{-1}$ .
- (b) Verify that  $F(z)$  can be written as

$$F(z) = \frac{z^{-2}}{1 - z^{-1}} + \frac{z^{-3}}{1 - z^{-1}}$$

Find the inverse Z-transform  $f[n]$  using the above expression.



# Exercises Ch.10 z-transform

answer

**Pr 9.19** (a)  $F(z)$  is a proper rational function in positive powers of  $z$  as its numerator is of lower order than the denominator. If we convert it into negative powers,  $z^{-1}$ , we have

$$F(z) = \frac{z^{-2}(1 + z^{-1})}{1 - z^{-1}}$$

which is not proper rational in  $z^{-1}$  as its numerator is of higher order than its denominator.

(b) Using the above expression we have that

$$F(z) = \frac{z^{-2}}{1 - z^{-1}} + \frac{z^{-3}}{1 - z^{-1}}$$

which gives

$$f[n] = u[n - 2] + u[n - 3]$$

given that  $1/(1 - z^{-1})$  is the Z-transform of  $u[n]$  and  $z^{-2}$  and  $z^{-3}$  delay  $u[n]$  by 2 and 3 samples.

# Exercises Ch.10 z-transform

## Exercise 15

### partial fraction expansion

- (a) Find the inverse Z-transform of  $a/(1 - az^{-1})^2$ .
- (b) Suppose that the partial fraction expansion given by MATLAB is

$$X(z) = \frac{-1}{1 - 0.5z^{-1}} + \frac{1}{(1 - 0.5z^{-1})^2}$$

Determine the inverse  $x[n]$ .

# Exercises Ch.10 z-transform

answer

**Pr 9.23** (a) In the Z-transform table we find the pair

$$na^n u[n] \Leftrightarrow \frac{az^{-1}}{(1 - az^{-1})^2}.$$

To obtain  $a/(1 - az^{-1})^2$  we multiply the above Z-transform by  $z$ , i.e., in the time-domain we advance the signal by one to get  $(n + 1)a^{n+1}u[n + 1] = (n + 1)a^{n+1}u[n]$ , since at  $n = -1$  we get that  $n + 1 = 0$ . Thus the pair

$$(n + 1)a^{n+1}u[n] \Leftrightarrow \frac{a}{(1 - az^{-1})^2}.$$

(b) The given  $X(z)$  equals

$$X(z) = \frac{-(1 - 0.5z^{-1}) + 1}{(1 - 0.5z^{-1})^2} = \frac{0.5z^{-1}}{(1 - 0.5z^{-1})^2}$$

which as indicated at the beginning of the previous part corresponds to  $x[n] = 0.5^n nu[n]$ . From the partial expansion we have using the second pair

$$x[n] = -0.5^n u[n] + 2(n + 1)0.5^{(n+1)}u[n] = 0.5^n (-1 + 2 \times 0.5(n + 1))u[n] = 0.5^n nu[n]$$